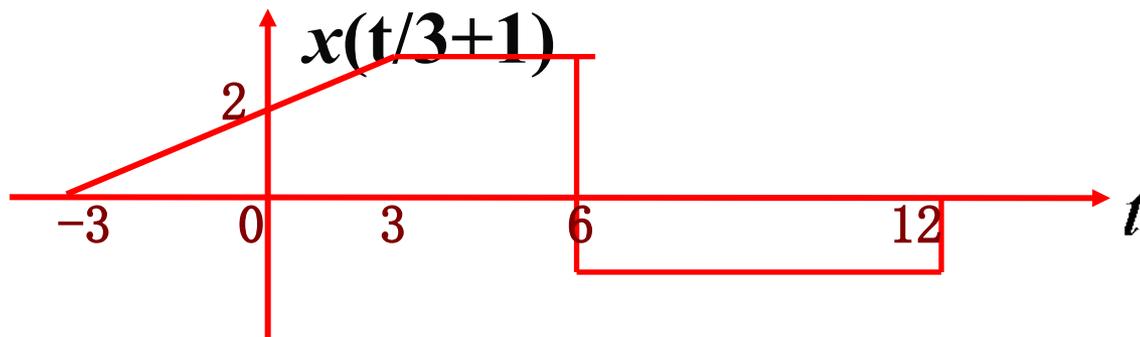
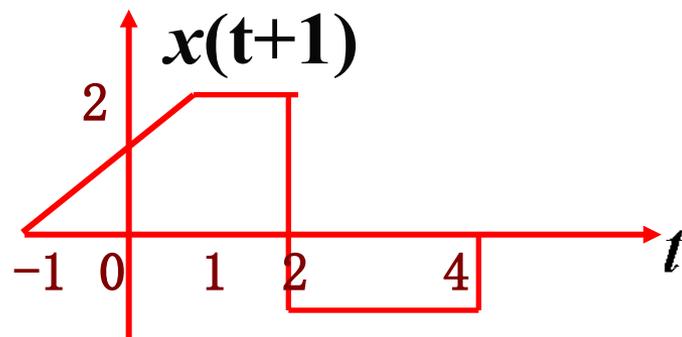
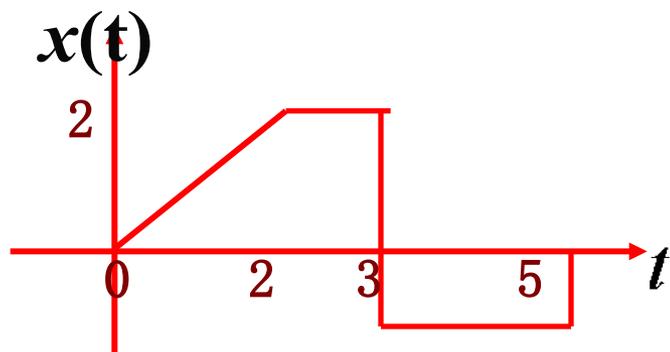


# 信号与系统陈后金版答案完整 版

2-5: (4)



2-9:  $x(t) = e^{-t}[u(t-1) - u(t-2)] + t\delta(t-3)$ , 求  $x^{(-1)}(t), x'(t)$

Q  $x(t) = e^{-t}[u(t-1) - u(t-2)] + 3\delta(t-3)$

$$\therefore x^{(-1)}(t) = \int_{-\infty}^t \{e^{-\tau}[u(\tau-1) - u(\tau-2)] + 3\delta(\tau-3)\} d\tau$$

$$x^{(-1)}(t) = \int_{-\infty}^t e^{-\tau}[u(\tau-1) - u(\tau-2)] d\tau + 3u(t-3)$$

$$\int_{-\infty}^t e^{-\tau}[u(\tau-1) - u(\tau-2)] d\tau = \begin{cases} 0, t < 1 \\ \int_1^t e^{-\tau} d\tau, 1 < t < 2 \\ \int_1^2 e^{-\tau} d\tau, t > 2 \end{cases}$$

$$\int_{-\infty}^t e^{-\tau}[u(\tau-1) - u(\tau-2)] d\tau = \begin{cases} 0, t < 1 \\ e^{-1} - e^{-t}, 1 < t < 2 \\ e^{-1} - e^{-2}, t > 2 \end{cases}$$

$$\therefore x^{(-1)}(t) = (e^{-1} - e^{-t})[u(t-1) - u(t-2)] + (e^{-1} - e^{-2})u(t-2) + 3u(t-3)$$

2-9:  $x(t) = e^{-t}[u(t-1) - u(t-2)] + t\delta(t-3)$ , 求  $x^{(-1)}(t), x'(t)$

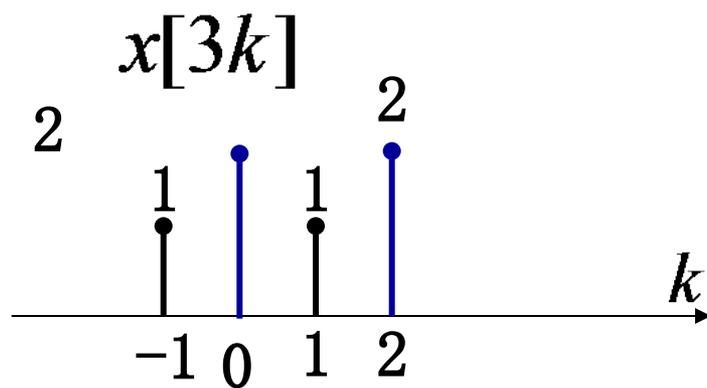
$$\therefore x'(t) = e^{-t}[\delta(t-1) - \delta(t-2)] - e^{-t}[u(t-1) - u(t-2)] + 3\delta(t-3)$$

$$\begin{aligned} x'(t) &= e^{-1}\delta(t-1) - e^{-2}\delta(t-2) - e^{-t}[u(t-1) - u(t-2)] + 3\delta'(t-3) \\ &= -e^{-t}[u(t-1) - u(t-2)] + e^{-1}\delta(t-1) - e^{-2}\delta(t-2) + 3\delta'(t-3) \end{aligned}$$

2-11:(3)

$$x[k] = 0.9^k \{u[k] - u[k-5]\} = 0.9^k, 0 \leq k \leq 4$$

2-13:(3)



2-13:(4)

$$3-2 \quad g(t) = r(t) - 2r(t-1) + r(t-2)$$

$$Q \quad x^{(-1)}(t) = r(t) - r(t-1)$$

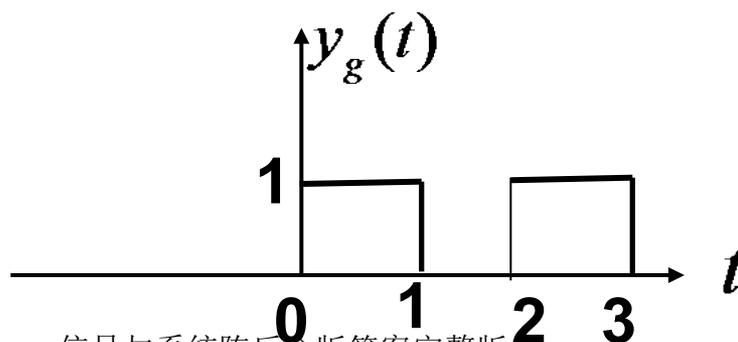
$$\therefore g(t) = x^{(-1)}(t) - x^{(-1)}(t-1)$$

**根据系统积分特性:**输入信号积分,输出也积分,有:

$$y_g(t) = y^{(-1)}(t) - y^{(-1)}(t-1)$$

$$= [u(t+1) + u(t+2)] - [u(t-1) + u(t-3)]$$

$$= [u(t+1) - u(t-1)] + [u(t-2) - u(t-3)]$$



**3-4** 已知离散时间LTI系统,输入  $x_1[k] = \delta[k-1]$  时,输出;

$y_1[k] = (\frac{1}{2})^{k-1} u[k-1]$ , 求当输入  $x_2[k] = 2\delta[k] + u[k]$  时系统响应  $y_2[k]$ 。

$$x_2[k] = 2x_1[k+1] + \sum_{n=-\infty}^k \delta[n]$$

$$x_2[k] = 2x_1[k+1] + \sum_{n=-\infty}^k x_1[n+1]$$

$$\therefore y_2[k] = 2y_1[k+1] + \sum_{n=-\infty}^k y_1[n+1]$$

$$\therefore y_2[k] = 2(\frac{1}{2})^k u[k] + \sum_{n=-\infty}^k (\frac{1}{2})^n u[n]$$

$$\therefore y_2[k] = 2(\frac{1}{2})^k u[k] + \sum_{n=0}^k (\frac{1}{2})^n = [2 + (\frac{1}{2})^k] u[k]$$

### 3-14(1)

$$\begin{aligned} & [\delta(t+1)+2\delta(t-1)]*[\delta(t-1)-\delta(t-3)] \\ & =\delta(t)+2\delta(t-2)-\delta(t-2)-2\delta(t-4) \end{aligned}$$

### 3-14(2)

$$\begin{aligned} & [u(t)-u(t-1)]*[u(t-2)-u(t-3)] \\ & =r(t-2)-r(t-3)-r(t-3)+r(t-4) \\ & =r(t-2)-2r(t-3)+r(t-4) \end{aligned}$$

$$\mathbf{3-20:} y''(t) + 7y'(t) + 10y(t) = 2x'(t) + 3x(t); x(t) = e^{-t}u(t);$$

$$y(0^-) = 1, y'(0^-) = 1$$

**解:** 1: 求冲激响应 $h(t)$ : 输入 $x(t) = \delta(t)$ , 有:

$$h''(t) + 7h'(t) + 10h(t) = 2\delta'(t) + 3\delta(t), t \geq 0$$

特征根为 $s_1 = -2, s_2 = -5$ , 又因为 $n > m$ , 所以:

$$\text{则 } h(t) = K_1 e^{-2t}u(t) + K_2 e^{-5t}u(t)$$

$$\begin{aligned} h'(t) &= -2K_1 e^{-2t}u(t) + K_1 \delta(t) - 5K_2 e^{-5t}u(t) + K_2 \delta(t) \\ &= -2K_1 e^{-2t}u(t) - 5K_2 e^{-5t}u(t) + (K_1 + K_2)\delta(t) \end{aligned}$$

$$\begin{aligned} h''(t) &= 4K_1 e^{-2t}u(t) - 2K_1 \delta(t) + 25K_2 e^{-5t}u(t) - 5K_2 \delta(t) \\ &\quad + (K_1 + K_2)\delta'(t) \end{aligned}$$

代入方程有:

$$2K_2 \delta(t) + 5K_1 \delta(t) \therefore K_2 = 7/3; K_1 = -1/3; 2\delta'(t) + 3\delta(t)$$

2:求零输入响应:

特征根为 $s_1 = -2, s_2 = -5$ ;所以:

则  $y_{zi}(t) = K_1 e^{-2t} + K_2 e^{-5t}, t \geq 0^-$

利用初始条件,有:

$$y(0^-) = K_1 + K_2 = 1$$

$$y'(0^-) = -2K_1 - 5K_2 = 1 \Rightarrow K_1 = 2, K_2 = -1$$

$$\therefore y_{zi}(t) = 2e^{-2t} - e^{-5t}, t \geq 0^-$$

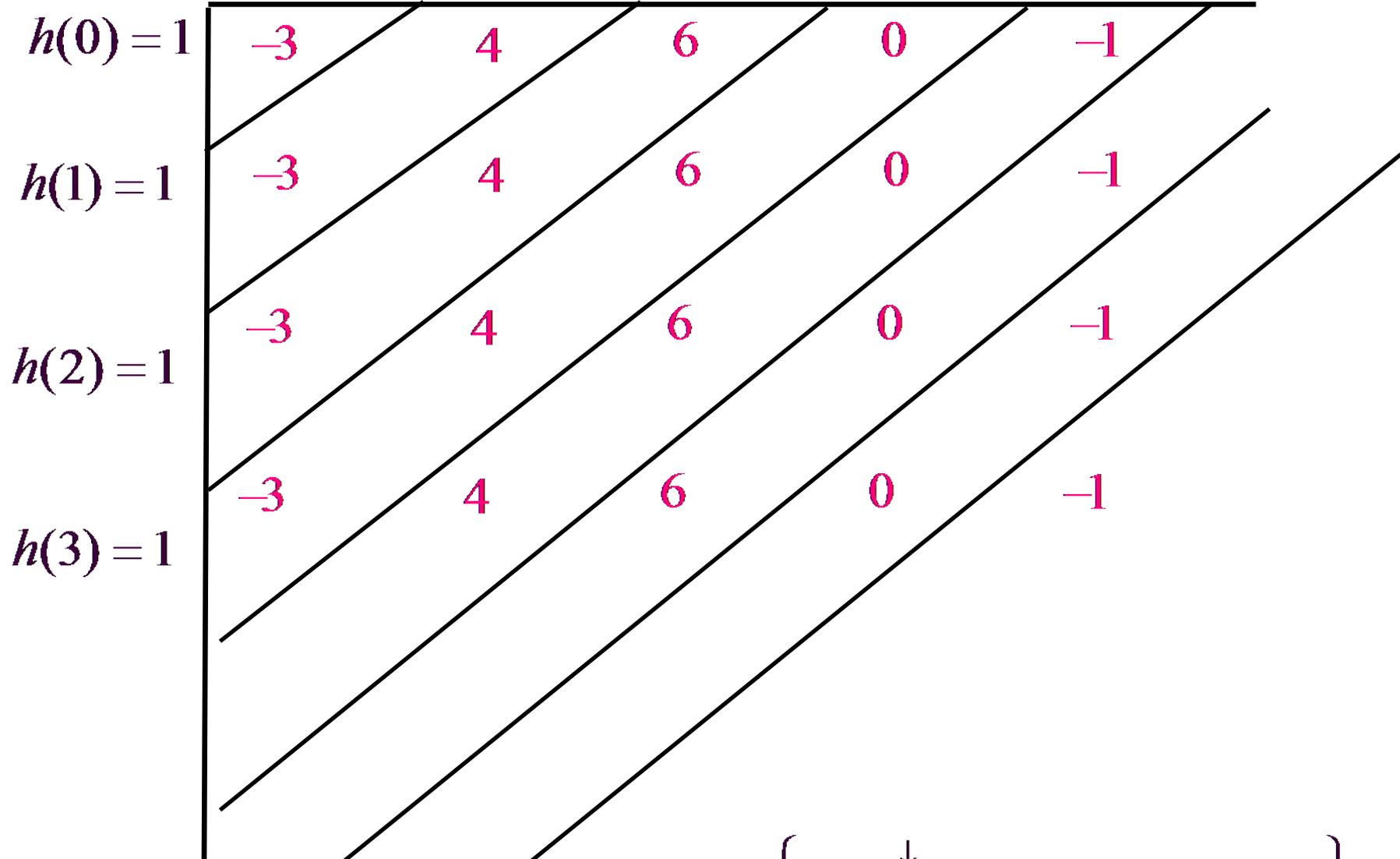
### 3:求零状态响应:

$$\begin{aligned}y_{zs}(t) &= x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau \\&= \int_{-\infty}^{\infty} \left[-\frac{1}{3}e^{-2\tau}u(\tau) + \frac{7}{3}e^{-5\tau}u(\tau)\right]e^{-(t-\tau)}u(t-\tau)d\tau \\&= \int_0^{\infty} \left[-\frac{1}{3}e^{-2\tau} + \frac{7}{3}e^{-5\tau}\right]e^{-(t-\tau)}d\tau \\&= \left(\frac{1}{4}e^{-t} + \frac{1}{3}e^{-2t} - \frac{7}{12}e^{-5t}\right)u(t)\end{aligned}$$

### 4:求全响应:

$$y(t) = y_{zi}(t) + y_{zs}(t)$$

**3-28:**  $x(-1) = -3$   $x(0) = 4$   $x(1) = 6$   $x(2) = 0$   $x(3) = -1$



$$\therefore y[k] = \left\{ -3, \underset{\downarrow}{1}, 7, 7, 9, 5, -1, -1 \right\}$$

**3-31:**  $y[k] - \frac{5}{6}y[k-1] + \frac{1}{6}y[k-2] = x[k], y(-1) = 0, y(-2) = 1,$   
 $x[k] = u[k]$

**解: (1)** 根据单位脉冲响应的定义, 应满足方程:

$$h[k] - \frac{5}{6}h[k-1] + \frac{1}{6}h[k-2] = \delta[k]$$

第一步: 求等效初始条件:

$$Qh[-1] = 0, h[-2] = 0$$

$$h[k] = [C_1 \left(\frac{1}{2}\right)^k + C_2 \left(\frac{1}{3}\right)^k] u[k]$$

代入等效初始条件:

第二步  $h[0] = C_1 + C_2$

特征方  $h[1] = h[k] = [3\left(\frac{1}{2}\right)^k - 2\left(\frac{1}{3}\right)^k] u[k] = 3, C_2 = -2$

## (2) :(a) 计算零输入响应:

特征方程为:  $r^2 - 5r/6 + 1/6 = 0$

$$\therefore r_1 = 1/2, r_2 = 1/3$$

则  $y_{zi}[k] = C_1 \left(\frac{1}{2}\right)^k + C_2 \left(\frac{1}{3}\right)^k, k \geq 0$

代入初始条件,有:

$$y[-1] = 2C_1 + 3C_2 = 0$$

$$y[-2] = 4C_1 + 9C_2 = 1 \Rightarrow C_1 = -1/2, C_2 = 1/3$$

则  $y_{zi}[k] = -\frac{1}{2} \left(\frac{1}{2}\right)^k + \frac{1}{3} \left(\frac{1}{3}\right)^k, k \geq 0$

$$= -\left(\frac{1}{2}\right)^{k+1} + \left(\frac{1}{3}\right)^{k+1}, k \geq 0$$

## (2) (b) 计算零状态响应:

$$\begin{aligned}y_{zs}[k] &= \sum_{n=-\infty}^{\infty} x[n]h[k-n] = u[k] * \left( 3\left(\frac{1}{2}\right)^k - 2\left(\frac{1}{3}\right)^k \right) u[k] \\&= \sum_{n=-\infty}^{\infty} u[n] \cdot \left( 3\left(\frac{1}{2}\right)^{k-n} - 2\left(\frac{1}{3}\right)^{k-n} \right) u[k-n] \\&= \sum_{n=0}^k \left( 3\left(\frac{1}{2}\right)^{k-n} - 2\left(\frac{1}{3}\right)^{k-n} \right) \\&= \sum_{n=0}^k 3\left(\frac{1}{2}\right)^{k-n} - \sum_{n=0}^k 2\left(\frac{1}{3}\right)^{k-n} \\&= \left[ 3 - 3\left(\frac{1}{2}\right)^k + \left(\frac{1}{3}\right)^k \right] u[k]\end{aligned}$$

完全响应:

$$y[k] = y_{zi}[k] + y_{zs}[k]$$

$$= \left[ \frac{1}{2} - \frac{7}{2} \left(\frac{1}{2}\right)^k + \frac{4}{3} \left(\frac{1}{3}\right)^k \right] u[k]$$

### (3) 计算固有响应与强迫响应:

完全响应:  $y[k] = \left[ \frac{1}{2} - \frac{7}{2} \left(\frac{1}{2}\right)^k + \frac{4}{3} \left(\frac{1}{3}\right)^k \right] u[k]$

固有响应:  $y_h[k] = \left[ -\frac{7}{2} \left(\frac{1}{2}\right)^k + \frac{4}{3} \left(\frac{1}{3}\right)^k \right] u[k]$

强迫响应:  $y_p[k] = \frac{1}{2} u[k]$

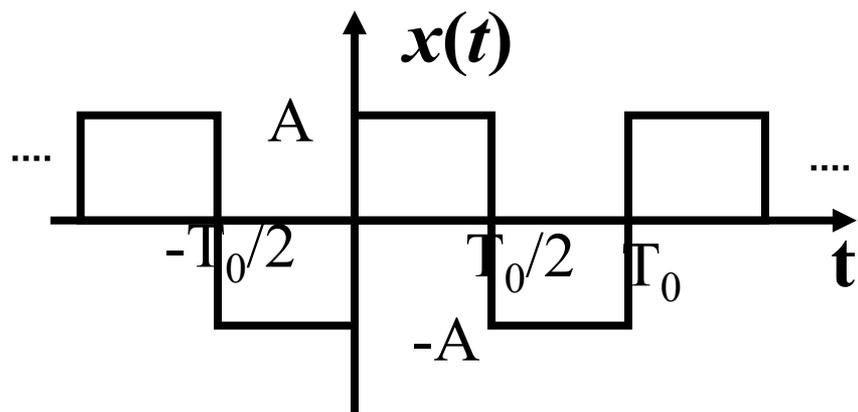
### (4) 计算瞬态响应与稳态响应:

瞬态响应:  $y_t[k] = \left[ -\frac{7}{2} \left(\frac{1}{2}\right)^k + \frac{4}{3} \left(\frac{1}{3}\right)^k \right] u[k]$

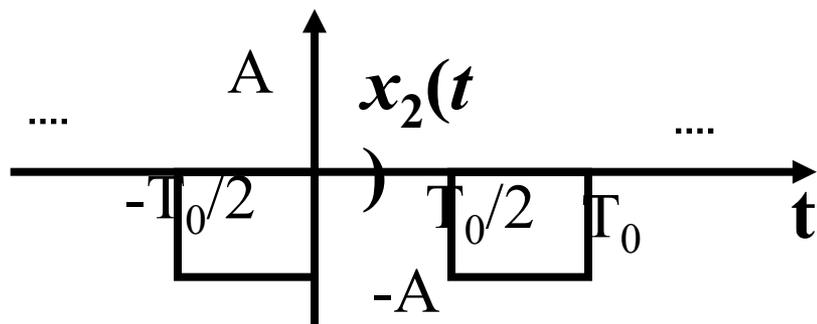
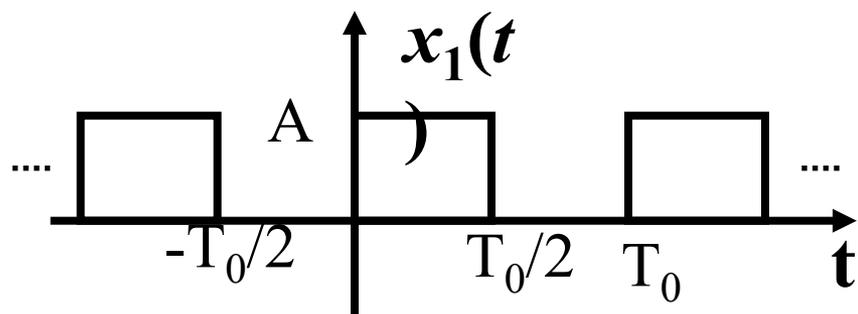
稳态响应:  $y_s[k] = \frac{1}{2} u[k]$

# 第四章

## 4-5(d)波形如图:

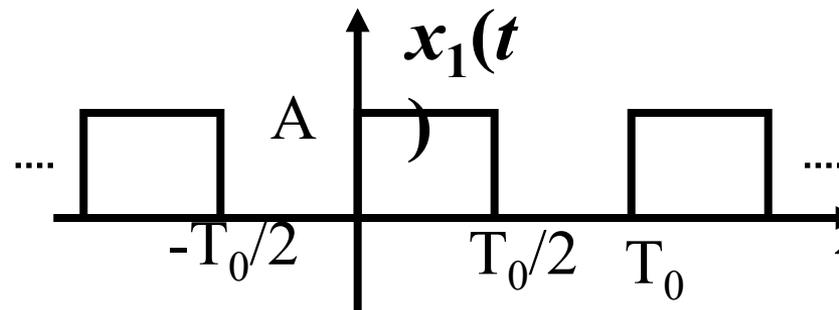


$$x(t) = x_1(t) + x_2(t)$$



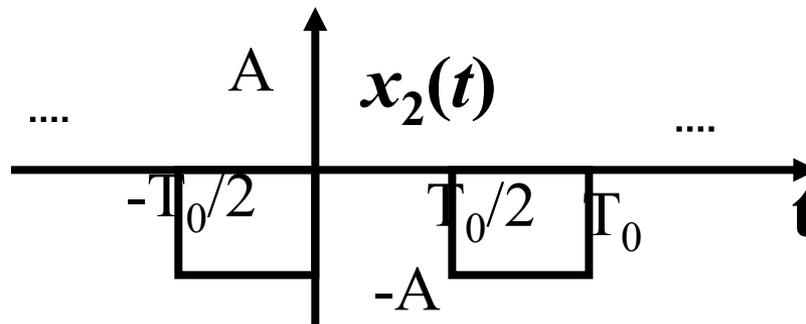
$x_1(t)$ 的傅里叶级数系数为：

$$a_n = \frac{AT_0}{2T_0} \text{Sa}\left(\frac{n\omega_0 T_0}{4}\right) e^{-j\frac{n\omega_0 T_0}{4}}$$



$x_2(t)$ 的傅里叶级数系数为：

$$b_n = -\frac{AT_0}{2T_0} \text{Sa}\left(\frac{n\omega_0 T_0}{4}\right) e^{j\frac{n\omega_0 T_0}{4}}$$



$x(t)$ 的傅里叶级数系数为：

$$C_n = a_n + b_n = \frac{AT_0}{2T_0} \text{Sa}\left(\frac{n\omega_0 T_0}{4}\right) [e^{-j\frac{n\omega_0 T_0}{4}} - e^{j\frac{n\omega_0 T_0}{4}}]$$

$$= \frac{AT_0}{2T_0} \text{Sa}\left(\frac{n\omega_0 T_0}{4}\right) [-2j \sin\left(\frac{n\omega_0 T_0}{4}\right)]$$

$$= \frac{A}{2} \text{Sa}\left(\frac{n\pi}{2}\right) [-2j \sin\left(\frac{n\pi}{2}\right)]$$

$$4-8 \quad x(t) = 2 \cos(2\pi t - 3) + \sin(6\pi t)$$

$$x(t) \text{ 角频率 } \omega_0 = 2\pi$$

$$\text{利用欧拉公式: } x(t) = 2 \times \frac{1}{2} (e^{j(2\pi t - 3)} + e^{-j(2\pi t - 3)}) + \frac{1}{2j} (e^{j6\pi t} - e^{-j6\pi t})$$

$$= (e^{j(\omega_0 t - 3)} + e^{-j(\omega_0 t - 3)}) + \frac{1}{2j} (e^{j3\omega_0 t} - e^{-j3\omega_0 t})$$

$$= e^{-3j} e^{j\omega_0 t} + e^{3j} e^{-j\omega_0 t} + \frac{1}{2j} (e^{j3\omega_0 t} - e^{-j3\omega_0 t})$$

$$\therefore C_1 = e^{-3j}; \quad C_{-1} = e^{3j}$$

$$C_3 = \frac{1}{2j}; \quad C_{-3} = \frac{-1}{2j}$$

平均功率P为:

$$\therefore P = \sum_{n=-\infty}^{\infty} |C_n|^2 = 1 + 1 + \frac{1}{4} + \frac{1}{4} = 2.5$$

4-9: (1)  $x(t) = u(t) - u(t-2)$

解法一:  $u(t) \stackrel{FT}{\Leftrightarrow} \pi\delta(\omega) + \frac{1}{j\omega}$

利用时移性质:

$$u(t-2) \stackrel{FT}{\Leftrightarrow} \left[ \pi\delta(\omega) + \frac{1}{j\omega} \right] e^{-2j\omega} = \pi\delta(\omega) + \frac{1}{j\omega} e^{-2j\omega}$$

$$x(t) \stackrel{FT}{\Leftrightarrow} \left( \pi\delta(\omega) + \frac{1}{j\omega} \right) - \left[ \pi\delta(\omega) + \frac{1}{j\omega} e^{-2j\omega} \right] = \frac{1}{j\omega} (1 - e^{-2j\omega})$$

解法二:  $x(t) = p_2(t-1)$

$$Q \quad F \{ p_2(t) \} = 2Sa(\omega)$$

$$\therefore F \{ x(t) \} = 2Sa(\omega) e^{-j\omega}$$

$$4-9(4): x(t) = e^{-2t} [u(t) - u(t-2)]$$

$$\text{解: } x(t) = e^{-2t} u(t) - e^{-4} e^{-2(t-2)} u(t-2)$$

$$Q e^{-t} u(t) \stackrel{FT}{\Leftrightarrow} \frac{1}{j\omega + 2}$$

利用时移性质:

$$e^{-2(t-2)} u(t-2) \stackrel{FT}{\Leftrightarrow} \frac{1}{j\omega + 2} e^{-2j\omega}$$

$$\therefore F \{x(t)\} = \frac{1}{j\omega + 2} - \frac{e^{-4}}{j\omega + 2} e^{-2j\omega}$$

## 4-8(9):

$$x(t) = \frac{d}{dt} \left[ \frac{\sin(\pi t)}{\pi t} * \frac{\sin(2\pi t)}{\pi t} \right]$$

$$\text{Q } \frac{\sin(\pi t)}{\pi t} \stackrel{FT}{\Leftrightarrow} u(\omega + \pi) - u(\omega - \pi) = p_{2\pi}(\omega)$$

$$\frac{\sin(2\pi t)}{\pi t} \stackrel{FT}{\Leftrightarrow} u(\omega + 2\pi) - u(\omega - 2\pi) = p_{4\pi}(\omega)$$

$$\therefore x(t) = \frac{d}{dt} \left[ \frac{\sin(\pi t)}{\pi t} * \frac{\sin(2\pi t)}{\pi t} \right] \stackrel{FT}{\Leftrightarrow} j\omega [p_{2\pi}(\omega) \times p_{4\pi}(\omega)] = j\omega p_{2\pi}(\omega)$$

4-  $X(j\omega) = Sa^2(\omega\tau)$

13(3): 设  $x_1(t) \stackrel{FT}{\Leftrightarrow} X_1(j\omega) = Sa(\omega\tau)$

则:  $X(j\omega) = X_1(j\omega) \times X_1(j\omega)$

利用卷积性质有:

$$x(t) = x_1(t) * x_1(t)$$

由  $X_1(j\omega) = Sa(\omega\tau)$ , 有:  $x_1(t) = \frac{1}{2\tau} p_{2\tau}(t)$

$$\therefore x(t) = x_1(t) * x_1(t) = \frac{1}{4\tau^2} p_{2\tau}(t) * p_{2\tau}(t)$$

$$= \frac{1}{4\tau^2} [u(t+\tau) - u(t-\tau)] * [u(t+\tau) - u(t-\tau)]$$

$$= \frac{1}{4\tau^2} [r(t+2\tau) - r(t) - r(t-2\tau)]$$

以上内容仅为本文档的试下载部分，为可阅读页数的一半内容。如要下载或阅读全文，请访问：<https://d.book118.com/028060140006006076>