

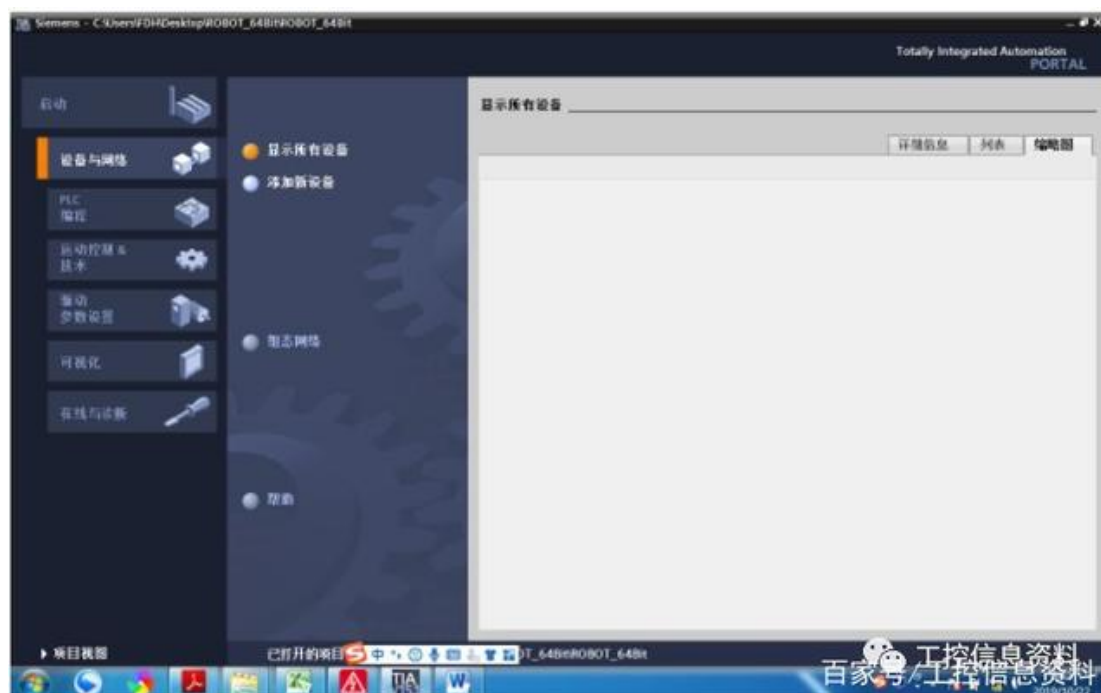
S7-1200PLC 与 FANUC 机器人 Profinet 通讯方法

一、PLC 组态

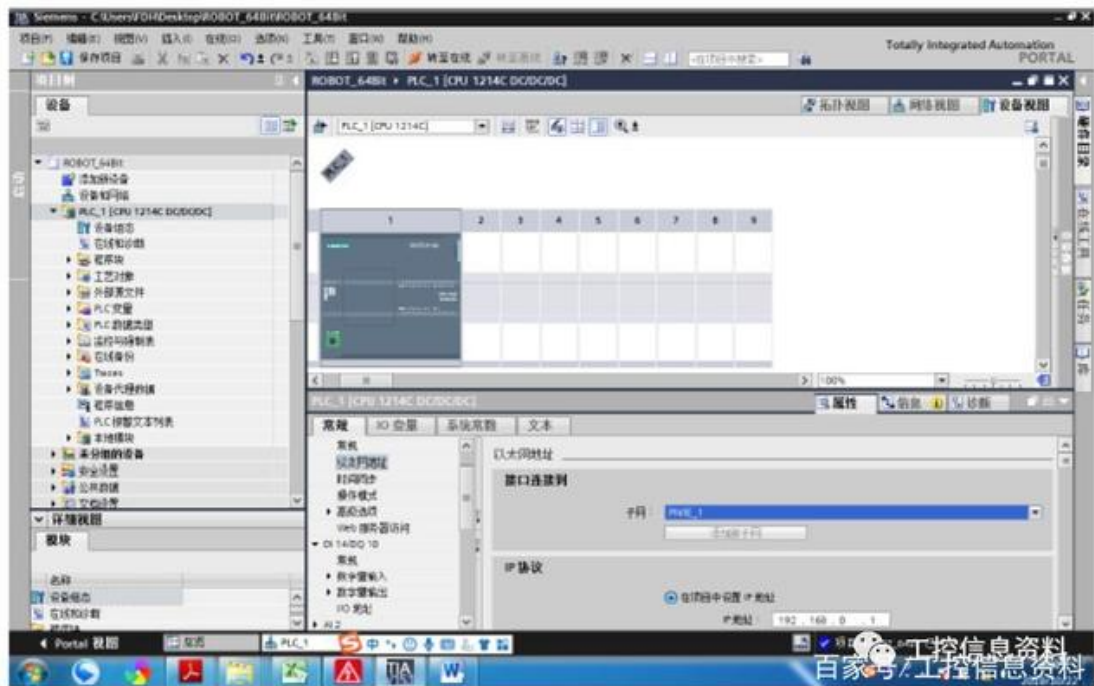
新建项目



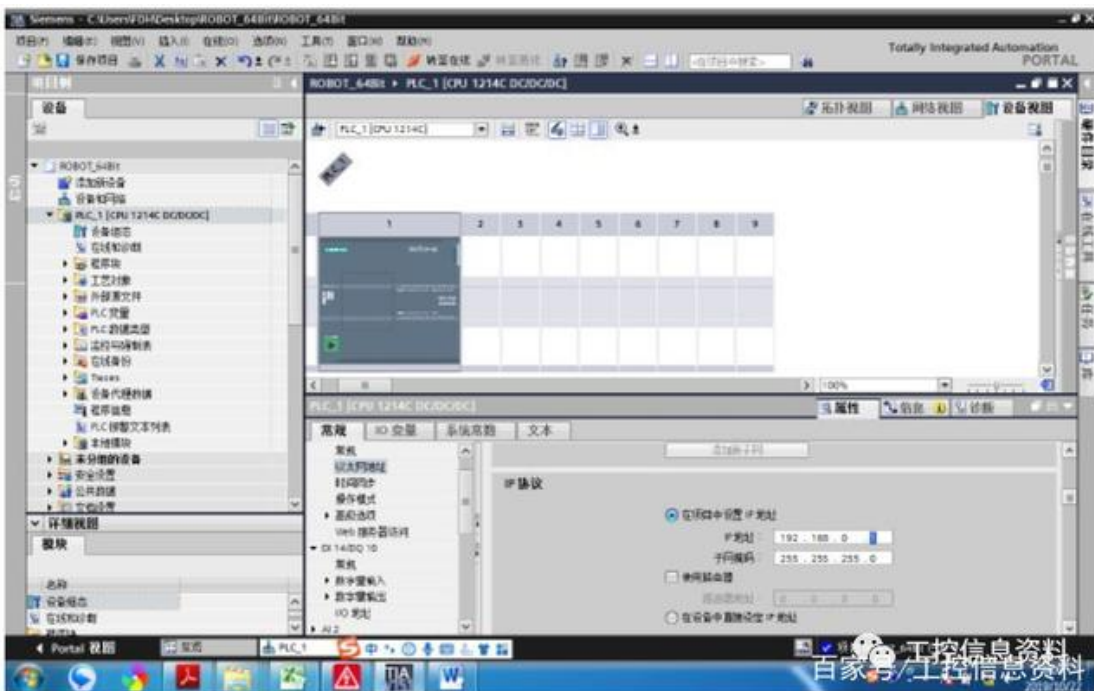
2. 添加新设备



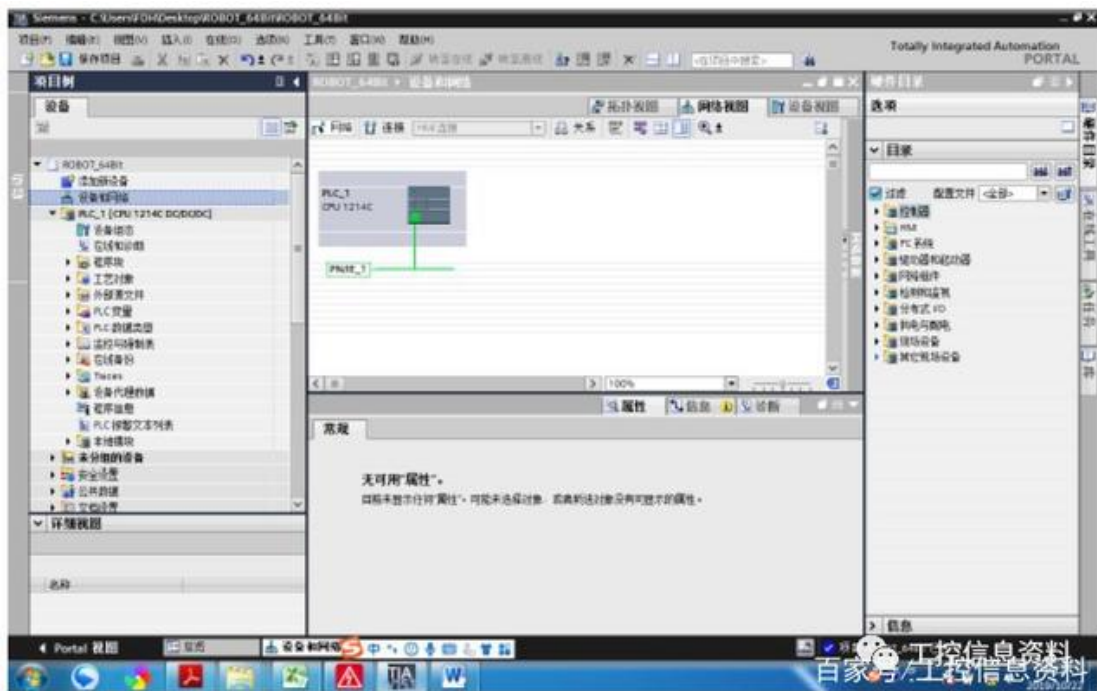




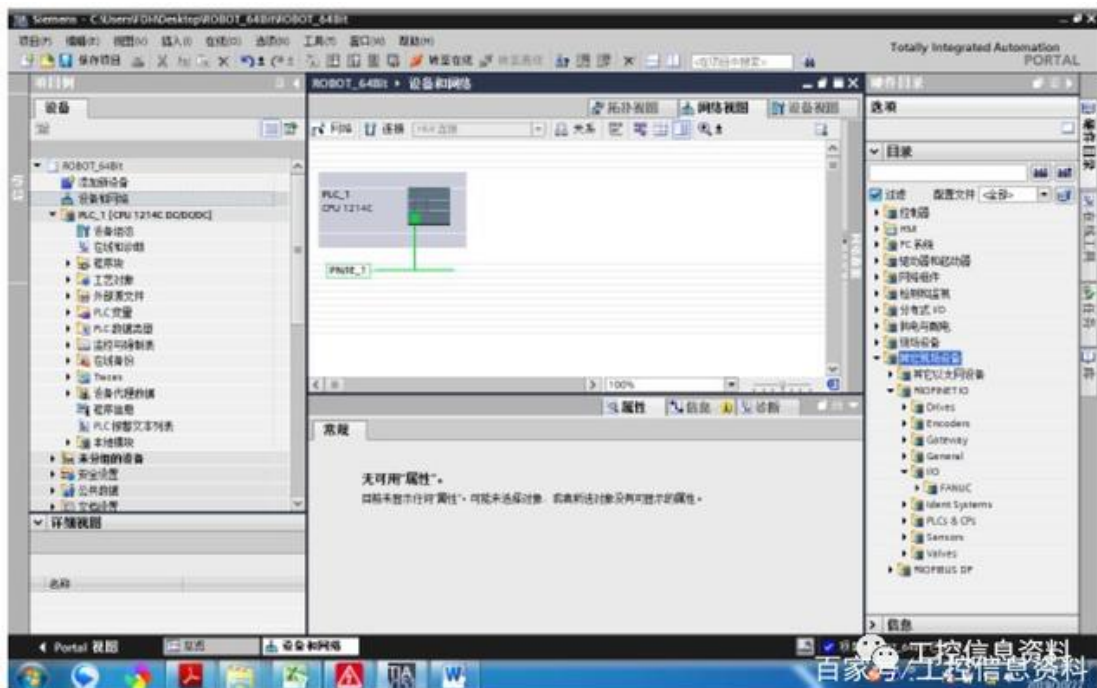
6.IP 协议



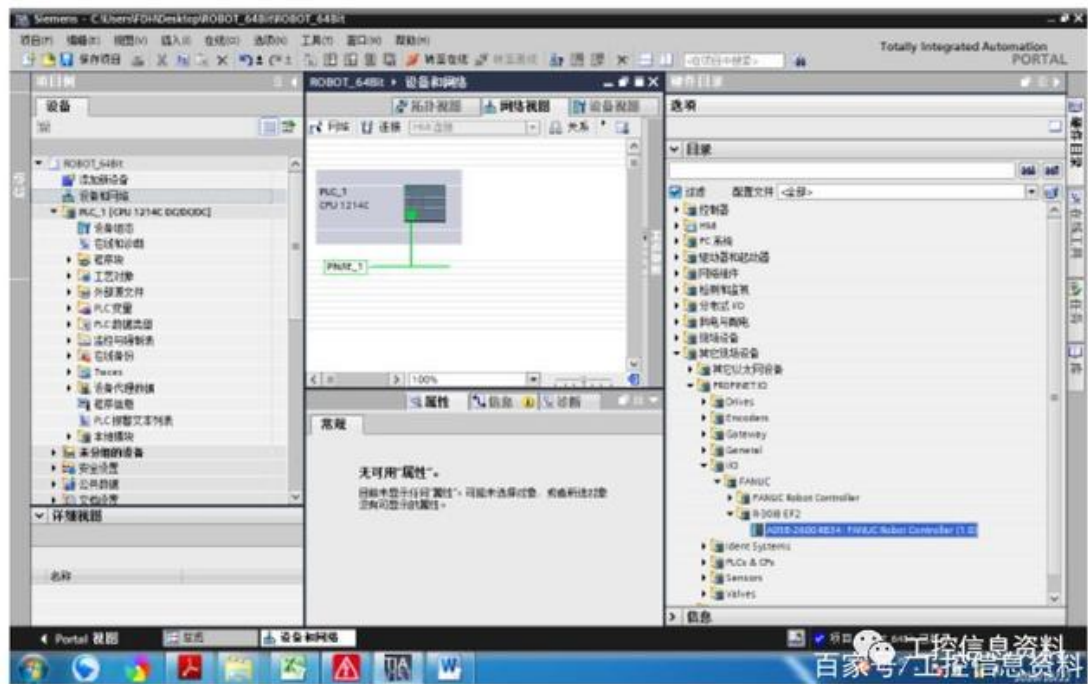
7.设备和网络



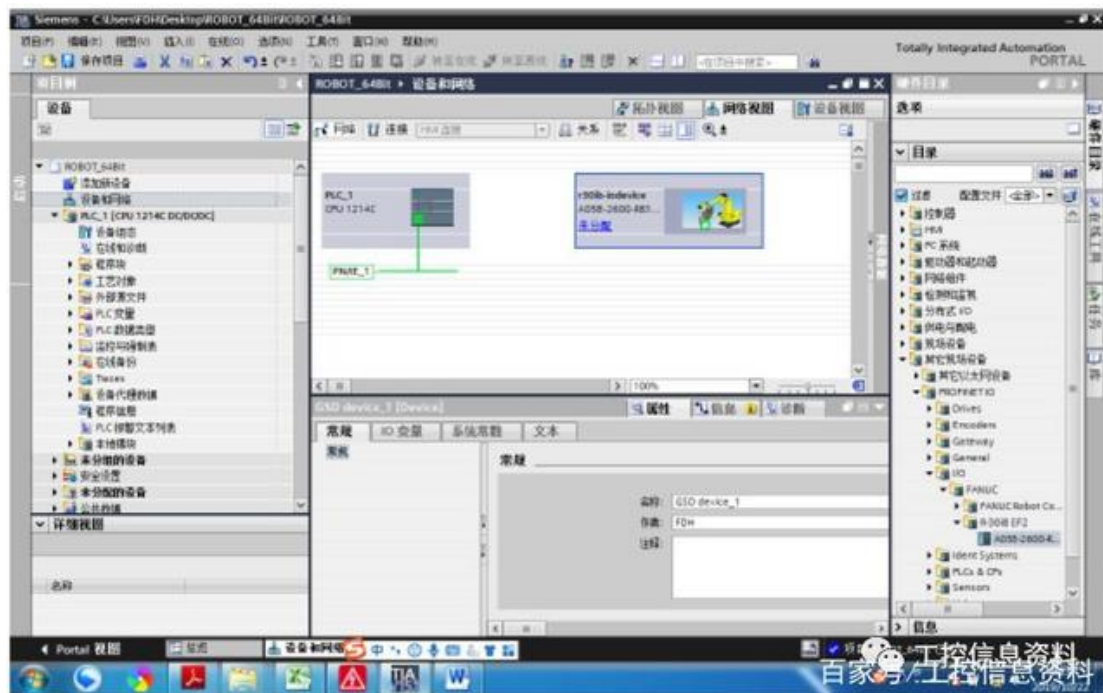
8.添加机器人



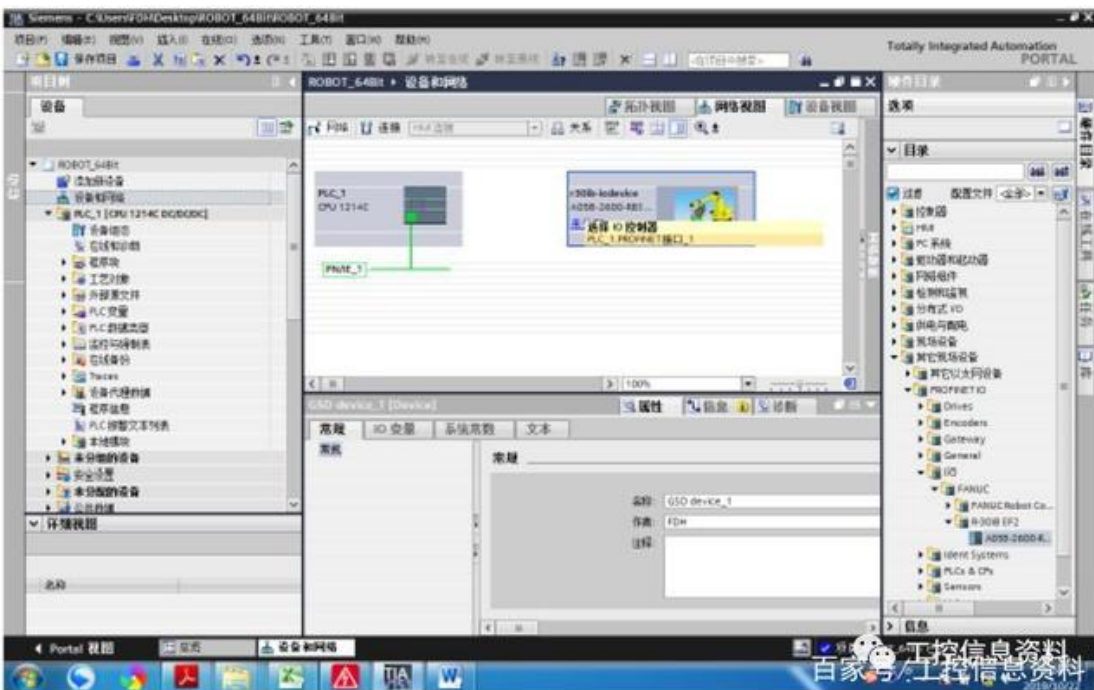
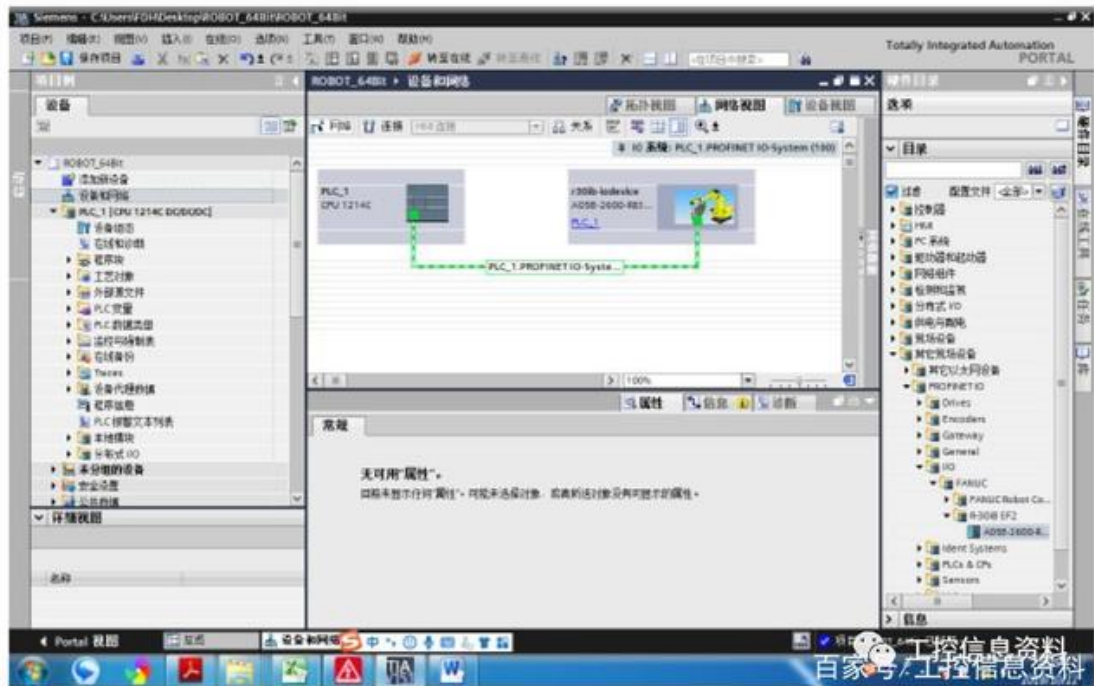
9.选择 硬件目录下→ 其他现场设备 → PROFINET IO→I/O→FANUC→R-30IB EF2→AO5B-2600-R843;FANUC Robot Controller(1.0)R843;



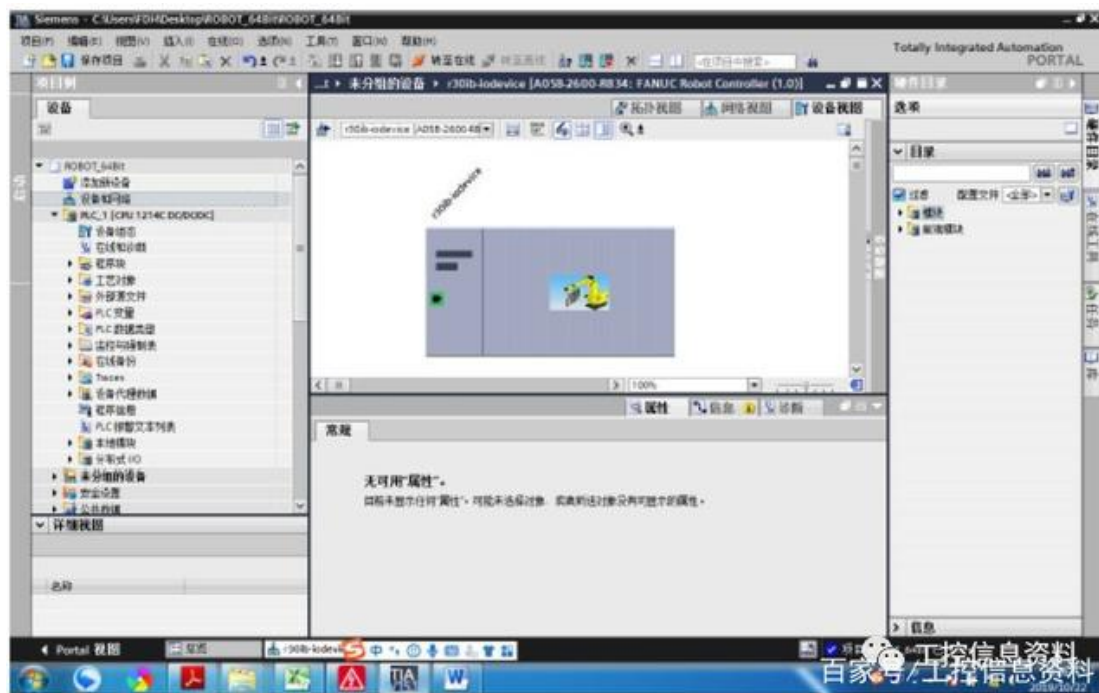
10.组网



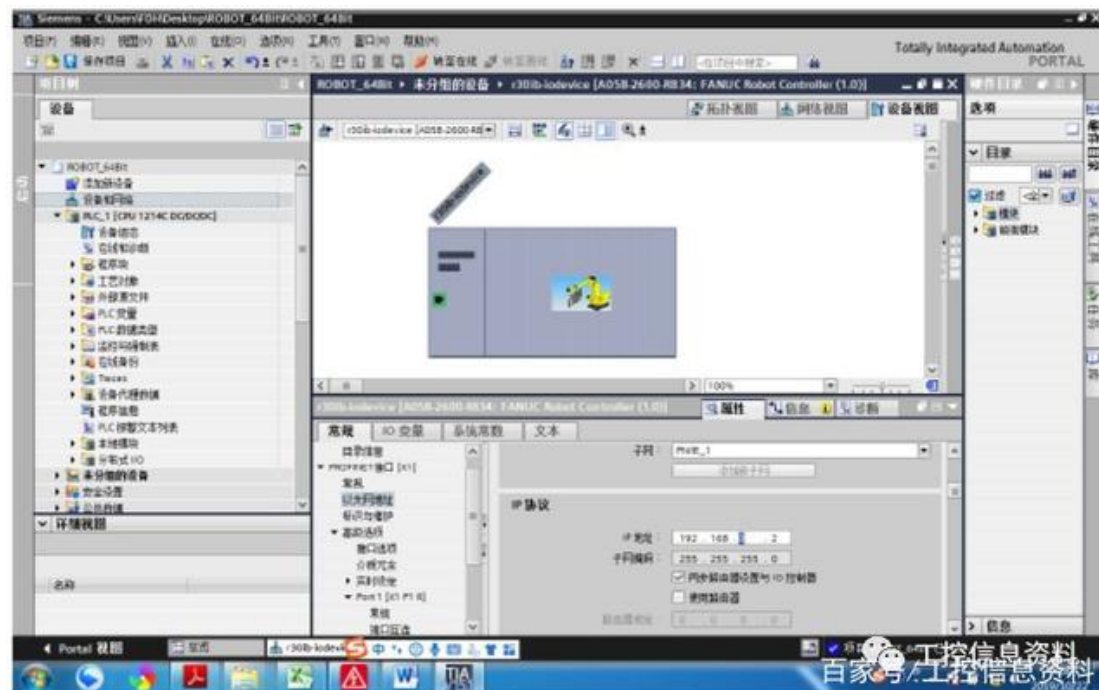
11.点击未分配



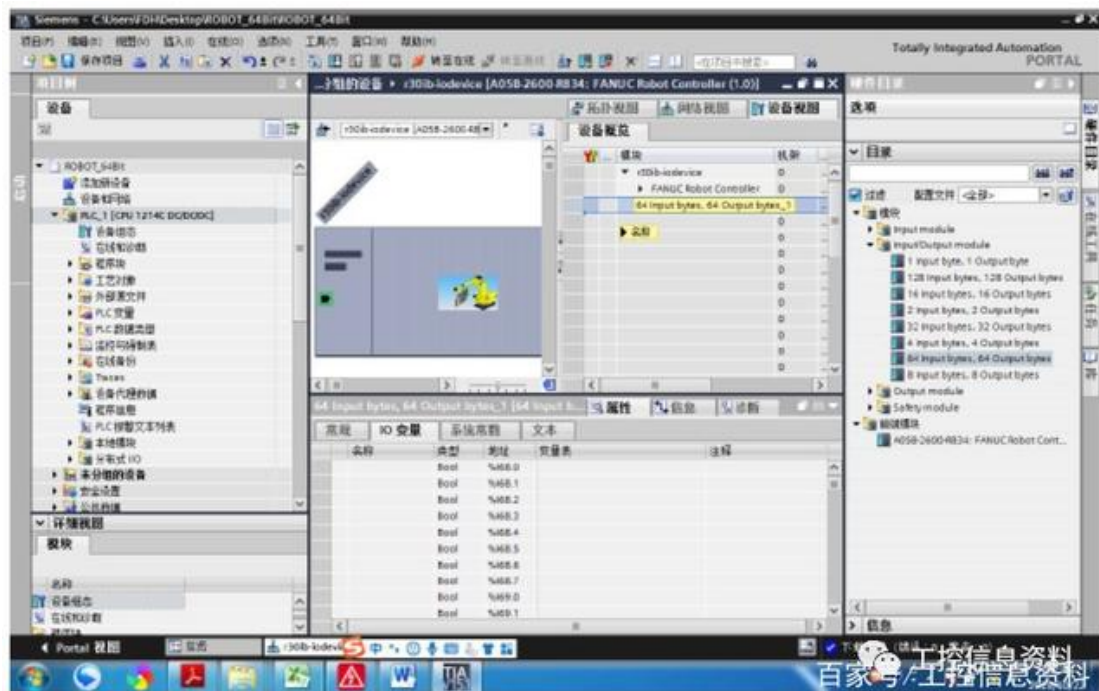
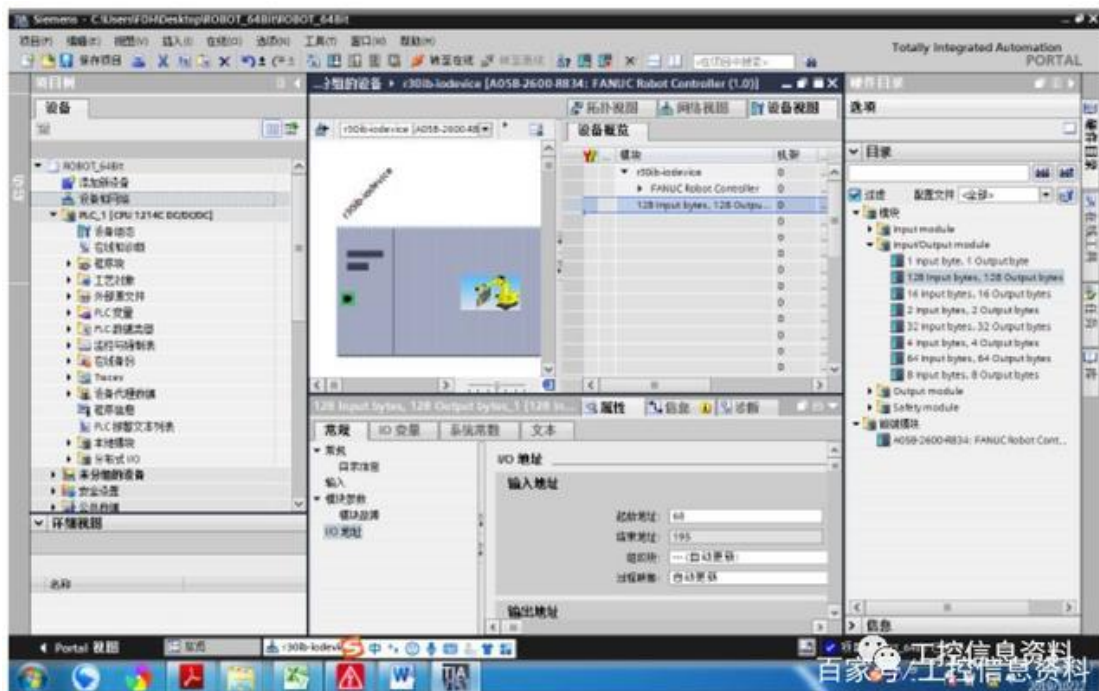
12.进入设备视图

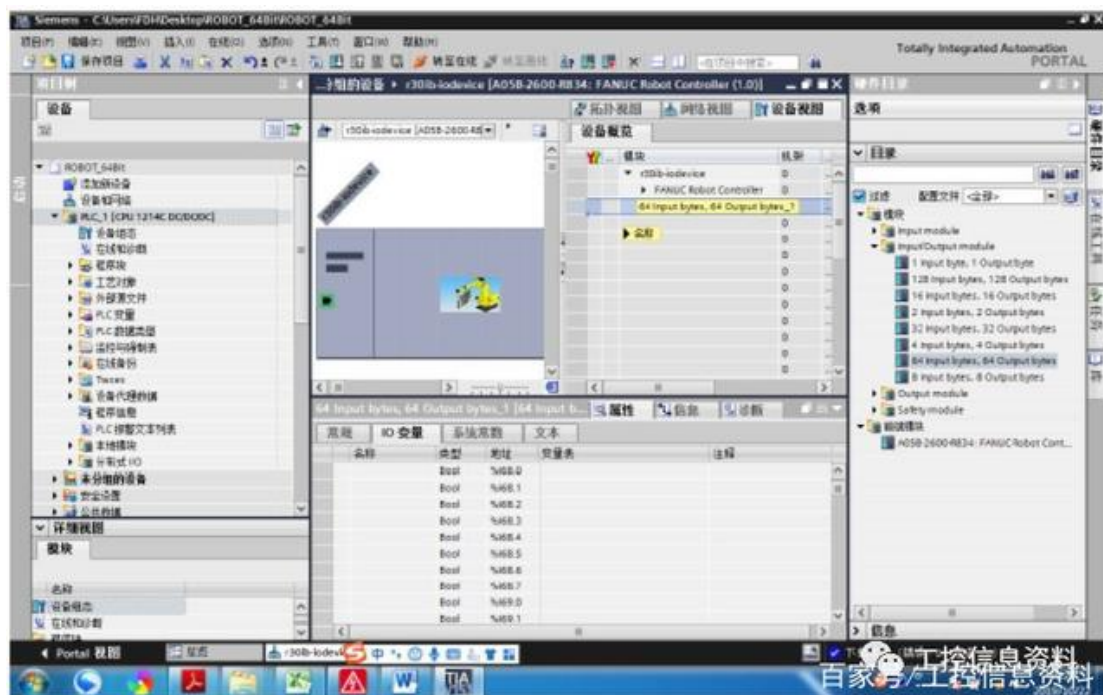


13.双击 r30ibr-iodevice (机器人图标)设置机器人 IP 地址

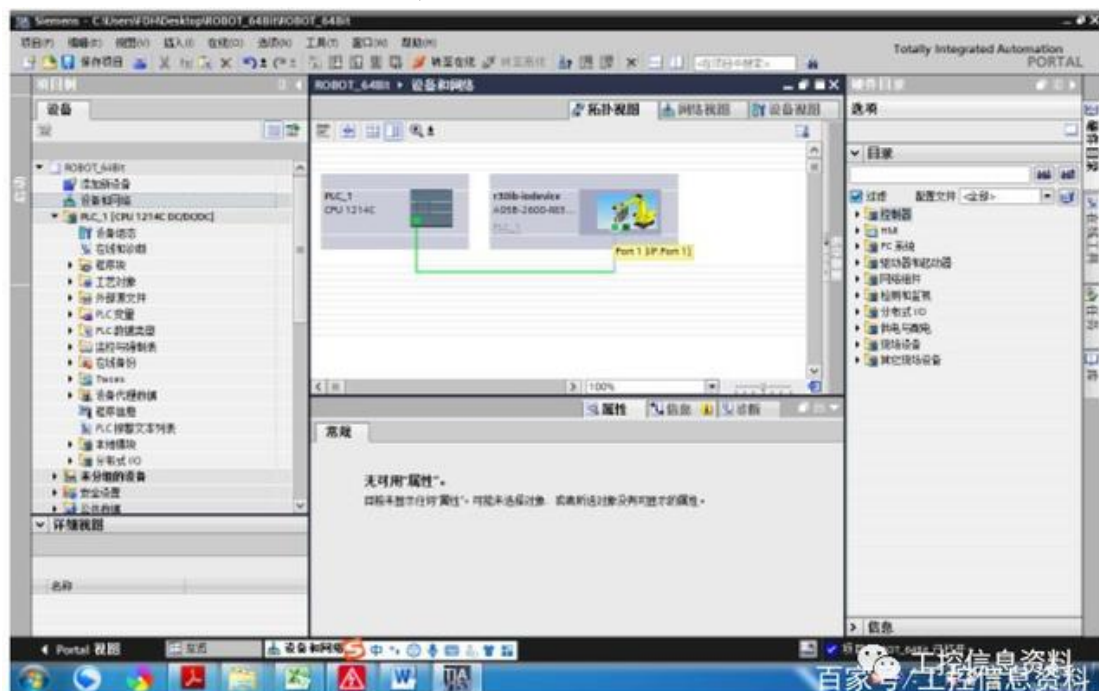


14.根据项目的需要添加通讯 i/o 的字节数

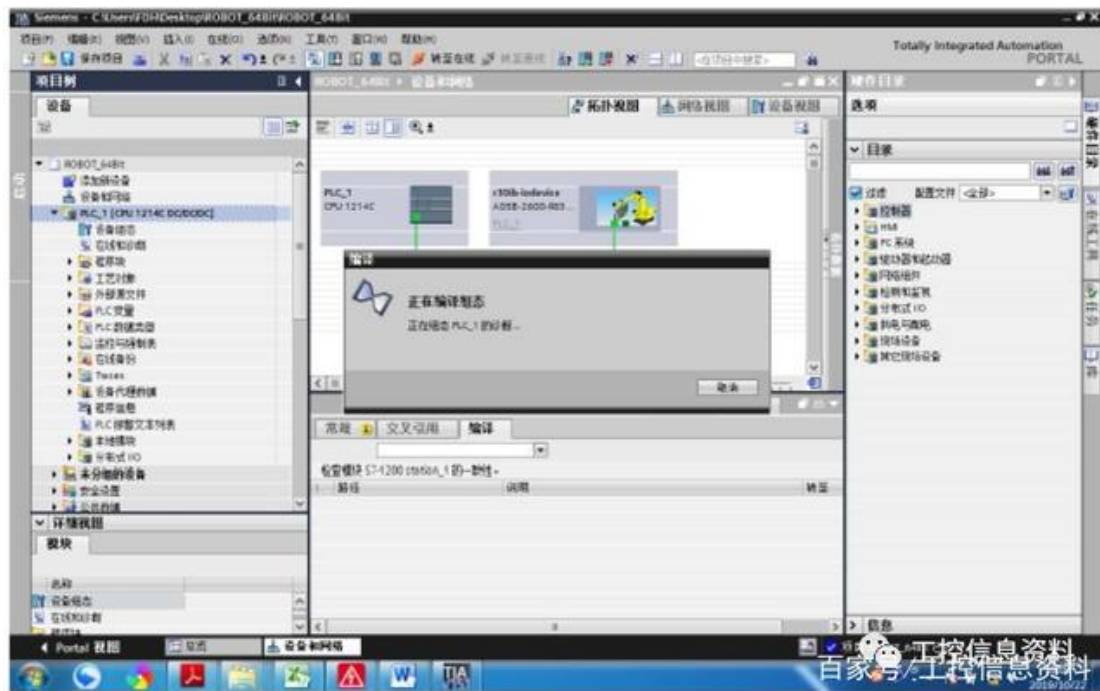




17.转到拓扑视图连接 PLC 到机器人



18.编译



19. 下载 PG/PC 要跟计算机的网卡对应



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