Mining Decision Trees from Data Streams

Tong Suk Man Ivy

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Data Streams

■ Characteristics

- Large volume of ordered data points, possibly infinite
- **n** Arrive continuously
- \blacksquare Fast changing
- Appropriate model for many applications:
	- **n** Phone call records
	- Network and security monitoring
	- **n** Financial applications (stock exchange)
	- Sensor networks

Problems in Mining Data Streams

- Traditional data mining techniques usually require
	- \blacksquare Entire data set to be present
	- \blacksquare Random access (or multiple passes) to the data
	- \blacksquare Much time per data item
- Challenges of stream mining
	- \blacksquare Impractical to store the whole data
	- \blacksquare Random access is expensive
	- **Simple calculation per data due to time and space** constraints

Classification of Stream Data

N VFDT algorithm

■ "Mining High-Speed Data Streams", KDD 2000. Pedro Domingos, Geoff Hulten

■ CVFDT algorithm (window approach)

■ "Mining *Time-Changing* Data Streams", KDD 2001. Geoff Hulten, Laurie Spencer, Pedro Domingos

Hoeffding Trees

Definitions

■ A classification problem is defined as: \blacksquare N is a set of training examples of the form (x, y) \blacksquare x is a vector of d attributes \blacksquare y is a discrete class label Goal: To produce from the examples a model y=f(x) that predict the classes y for future examples x with high accuracy

Decision Tree Learning

- \blacksquare One of the most effective and widely-used classification methods
- \blacksquare Induce models in the form of decision trees
	- \blacksquare Each node contains a test on the attribute
	- \blacksquare Each branch from a node corresponds to a possible outcome of the test
	- Each leaf contains a class prediction
	- \blacksquare A decision tree is learned by recursively replacing leaves by test nodes, starting at the root

Challenges

- Classic decision tree learners assume all training data can be simultaneously stored in main memory
- Disk-based decision tree learners repeatedly read training data from disk sequentially
	- \blacksquare Prohibitively expensive when learning complex trees
- Goal: design decision tree learners that read each example at most once, and use a small constant time to process it

Key Observation

- I In order to find the best attribute at a node, it may be sufficient to consider only a small subset of the training examples that pass through that node.
	- Given a stream of examples, use the first ones to choose the root attribute.
	- \blacksquare Once the root attribute is chosen, the successive examples are passed down to the corresponding leaves, and used to choose the attribute there, and so on recursively.
- Use Hoeffding bound to decide how many examples are enough at each node

Hoeffding Bound

 \blacksquare Consider a random variable a whose range is R ■ Suppose we have n observations of a **Nean:** \overline{a} **Hoeffding bound states:** With probability 1- \triangle , the true mean of a is at least

> $a-e$, where $\varepsilon = \sqrt{\frac{R^2 \ln(1/\delta)}{2n}}$

How many examples are enough?

- \blacksquare Let $G(X_i)$ be the heuristic measure used to choose test attributes (e.g. Information Gain, Gini Index)
- \blacksquare *X_a* : the attribute with the highest attribute evaluation value after seeing n examples.
- \blacksquare X_b : the attribute with the second highest split evaluation function value after seeing n examples.
- Given a desired \triangle , if $\Delta G = G(X_a) G(X_b) > \varepsilon$ after seeing n examples at a node,
	- **n** Hoeffding bound guarantees the true $\Delta G > = \Delta G \varepsilon > 0$, with probability $1-\frac{\pi}{2}$.
	- **n** This node can be split using X_a , the succeeding examples will be passed to the new leaves.

$$
\varepsilon = \sqrt{\frac{R^2 \ln(1/\delta)}{2n}}
$$

Algorithm

- \blacksquare Calculate the information gain for the attributes and determines the best two attributes
	- **n** Pre-pruning: consider a "null" attribute that consists of not splitting the node
- \blacksquare At each node, check for the condition

$$
\Delta \overline{G} = \overline{G}(X_a) - \overline{G}(X_b) > \varepsilon
$$

- \blacksquare If condition satisfied, create child nodes based on the test at the node
- **n If not, stream in more examples and perform** calculations till condition satisfied

Performance Analysis

- \blacksquare p: probability that an example passed through DT to level i will fall into a leaf at that point
- The expected disagreement between the tree produced by Hoeffding tree algorithm and that produced using infinite examples at each node is no greater than \mathcal{L}/p .
- Required memory: O(leaves * attributes * values * classes)

VFDT

VFDT (Very Fast Decision Tree)

- n A decision-tree learning system based on the Hoeffding tree algorithm
- \blacksquare Split on the current best attribute, if the difference is less than a user-specified threshold

 \blacksquare Wasteful to decide between identical attributes

- Compute G and check for split periodically
- Memory management
	- Memory dominated by sufficient statistics
	- **n** Deactivate or drop less promising leaves when needed
- Bootstrap with traditional learner
- Rescan old data when time available

VFDT(2)

■ Scales better than pure memory-based or pure disk-based learners

- **n Access data sequentially**
- \blacksquare Use subsampling to potentially require much less than one scan
- \blacksquare VFDT is incremental and anytime
	- \blacksquare New examples can be quickly incorporated as they arrive
	- \blacksquare A usable model is available after the first few examples and then progressively defined

Experiment Results (VFDT vs. C4.5)

- Compared VFDT and C4.5 (Quinlan, 1993)
- Same memory limit for both (40 MB)
	- 100k examples for C4.5
- **N** VFDT settings: δ= 10⁻⁷, τ= 5%, n_{min}=200
- Domains: 2 classes, 100 binary attributes
- \blacksquare Fifteen synthetic trees 2.2k 500k leaves
- \blacksquare Noise from 0% to 30%

Experiment Results

Accuracy as a function of the number of training examples

Experiment Results

Tree size as a function of number of training examples 21

Mining Time-Changing Data Stream

- Most KDD systems, include VFDT, assume training data is a sample drawn from stationary distribution
- **n** Most large databases or data streams violate this assumption
	- Concept Drift: data is generated by a time-changing concept function, e.g.
		- \blacksquare Seasonal effects
		- Economic cycles
- Goal:
	- \blacksquare Mining continuously changing data streams
	- Scale well

Window Approach

- Common Approach: when a new example arrives, reapply a traditional learner to a sliding window of w most recent examples
	- \blacksquare Sensitive to window size
		- \blacksquare If w is small relative to the concept shift rate, assure the availability of a model reflecting the current concept
		- \blacksquare Too small w may lead to insufficient examples to learn the concept
	- \blacksquare If examples arrive at a rapid rate or the concept changes quickly, the computational cost of reapplying a learner may be prohibitively high.

CVFDT

CVFDT

■ CVFDT (Concept-adapting Very Fast Decision Tree learner)

- Extend VFDT
- Maintain VFDT's speed and accuracy
- Detect and respond to changes in the examplegenerating process

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